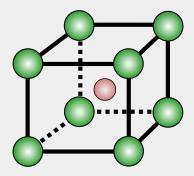
# **MACHINE LEARNING IN BIOINFORMATICS** GRAPH NEURAL NETWORKS

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- Graph Convolutional Neural Networks (GCNN)
- General graph neural networks (GNN)
- Graph isomorphisms and discriminative power of GNNs
- Advanced models and applications

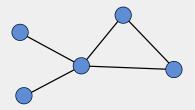
# GRAPH CONVOLUTIONAL NEURAL NETWORKS (GCNNS)

- Convolutions are not only restricted to image and time-series data
- Graph convolutions are used to model the interaction between nodes
- Let G = (N, E) denote a graph with nodes N and edges E
- How could we implement a convolution of G with a weight matrix W?
- The result of a convolution is again a graph<sup>1</sup>, i.e.

$$G' = G * W$$

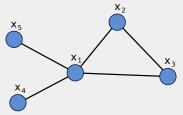
<sup>&</sup>lt;sup>1</sup>Remember that convolution on images also returns an image

■ Graph G with 5 nodes and 5 edges:



- We assign a feature vector  $x_i \in \mathbb{R}^p$  to the *i*-th node
- The feature vector can depend on the type of the node
- Nodes of the same type might share the same feature vector

■ Graph *G* with 5 nodes and 5 edges:



- We assign a feature vector  $x_i \in \mathbb{R}^p$  to the *i*-th node
- The feature vector can depend on the type of the node
- Nodes of the same type might share the same feature vector

- Let  $A = (a_{ij})_{ij} \in \mathbb{R}^{k \times k}$  denote the adjacency matrix of a graph with *k* nodes
- The strength of the connection between node *i* and *j* is given by a<sub>ij</sub>
- Self-connections  $a_{ii} \neq 0$  allow to incorporate the features of the nodes itself
- The convolution operation updates the feature vector of node *i* by summing over all neighbor nodes, i.e.

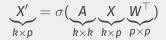
$$\mathbf{x}_{i}' = \sigma\left(\sum_{j} a_{ij} \mathbf{W} \mathbf{x}_{j}\right) = \sigma\left(\sum_{j \to i} \mathbf{W} \mathbf{x}_{j}\right)$$

where  $W \in \mathbb{R}^{p \times p}$  and  $\sigma$  is the activation function<sup>2</sup>

<sup>2</sup>Graph convolutions are *permutation equivariant* 

5

■ For the full graph we obtain



where  $X \in \mathbb{R}^{k \times p}$  is the matrix of *k* feature vectors

- Note that the weight matrix W does not depend on the size and connectivity of the graph
- W can be applied to multiple graphs and optimized during training of the graph convolutional neural network (GCNN)
- GCNNs typically apply multiple convolutions and afterwards compute summary statistics of the feature vectors, the result can then be used in a conventional neural network

<sup>2</sup>Many extensions and generalizations exist [Battaglia et al., 2018, Dwivedi et al., 2020]

# GCNN Generalizated Update Rules

#### **GRAPH CONVOLUTIONS - SELF-CONNECTIONS**

- Graph convolutional networks as introduced so far, can be efficiently computed, but are limited in their expressive power
- The same weight matrix *W* is used for all nodes
- A simple extension is to introduce a separate weight matrix V for self-connections

$$\mathbf{X}_{i}' = \sigma \left( \mathbf{V} \mathbf{X}_{i} + \sum_{j \to i} \mathbf{W} \mathbf{X}_{j} \right)$$

Note that now the sum over  $\{j \rightarrow i\}$  should not include any self-connections

#### **GRAPH CONVOLUTIONS - EDGE GATES**

- Another important generalization are edge gates [Marcheggiani and Titov, 2017]
- Edge gates allow the network to learn what edges are important for the graph learning task
- The update function is given by

$$\mathbf{x}'_i = \sigma \left( \sum_{j \to i} \eta_{ij} \odot \mathbf{W} \mathbf{x}_j \right)$$

where  $\odot$  denotes the element-wise multiplication (Hadamard product)

• The  $\eta_{ij} \in \mathbb{R}^p$  act as edge gates and are computed as

$$\eta_{ij} = \sigma \left( \mathsf{A} \mathsf{x}_i + \mathsf{B} \mathsf{x}_j \right)$$

#### **GRAPH CONVOLUTIONS - EDGE FEATURES**

- Even more general are networks that contain separate features on edges [Joshi et al., 2019]
- Node features and edge features e<sub>ij</sub> between nodes i and j are updated as follows

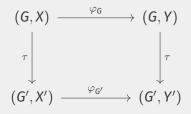
$$\begin{aligned} \mathbf{x}'_{i} &= \sigma \left( \sum_{j \to i} \eta_{ij} \odot \mathsf{W} \mathbf{x}_{j} \right) \\ \mathbf{e}'_{ij} &= \sigma \left( \mathsf{A} \mathbf{x}_{i} + \mathsf{B} \mathbf{x}_{j} + \mathsf{C} \mathbf{e}_{ij} \right) \\ \eta_{ij} &= \frac{\sigma(\mathbf{e}_{ij})}{\sum_{k} \sigma(\mathbf{e}_{ik}) + \epsilon} \end{aligned}$$

• Note that  $\eta_{ij}$  is a normalized version of  $\sigma(e_{ij})$ 

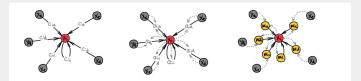
# GRAPH NEURAL NETWORKS (GNNS)

#### PERMUTATION EQUIVARIANCE ON GRAPHS

- Let  $X \in \mathbb{R}^{k \times p}$  be the feature matrix of a graph *G* with *k* nodes
- Let φ<sub>G</sub>(X) denote the result of applying a graph neural network φ<sub>G</sub> to X
- $\tau(G, X)$  denotes a row-permutation of X with corresponding relabeling of nodes in G
- We require that  $\varphi_{\rm G}$  is *equivariant* with respect to  $\tau$  (permutation equivariant), i.e.



#### GRAPH NEURAL NETWORKS (GNNS)



Three types of GNNs:

Convolution, Attention, Message passing

Update rule of GNNs [Bronstein et al., 2021]

$$\mathbf{x}'_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \to i} \psi(\mathbf{x}_i, \mathbf{x}_j)\right)$$

where  $\bigoplus$  is a permutation invariant aggregation function,  $\phi$  and  $\psi$  are learnable functions

#### **GRAPH NEURAL NETWORKS - GCNNs**

General update formula of GNNs [Bronstein et al., 2021]:

$$\mathbf{x}'_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \to i} \psi(\mathbf{x}_i, \mathbf{x}_j)\right)$$

where  $\oplus$  is a permutation invariant aggregation function

GCNNs are an instance of GNNs, because

$$\mathbf{x}'_{i} = \phi\left(\mathbf{x}_{i}, \bigoplus_{j \to i} \psi(\mathbf{x}_{i}, \mathbf{x}_{j})\right) = \sigma\left(\mathbf{V}\mathbf{x}_{i} + \sum_{j \to i} \mathbf{W}\mathbf{x}_{j}\right)$$

where  $\phi(\mathbf{x}_i, \mathbf{z}) = \sigma(\mathbf{V}\mathbf{x}_i + \mathbf{z})$ ,  $\bigoplus = \sum$ , and  $\psi(\mathbf{x}_i, \mathbf{x}_j) = \mathbf{W}\mathbf{x}_j$ 

#### **GRAPH NEURAL NETWORKS - SELF-ATTENTION**

General update formula of GNNs [Bronstein et al., 2021]:

$$\mathbf{x}'_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \to i} \psi(\mathbf{x}_i, \mathbf{x}_j)\right)$$

where  $\oplus$  is a permutation invariant aggregation function

Self-attention layers are characterized by

$$\psi(\mathbf{x}_i,\mathbf{x}_j) = \mathbf{a}(\mathbf{x}_i,\mathbf{x}_j)\psi'(\mathbf{x}_j)$$

where *a* denotes the attention mechanism that computes the similarity between  $x_i$  and  $x_j$  [Veličković et al., 2017]

The message  $\psi'(x_j)$  from node *j* is weighted by the attention value  $a(x_i^T, x_j)$ 

General update formula of GNNs [Bronstein et al., 2021]:

$$\mathbf{x}'_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \to i} \psi(\mathbf{x}_i, \mathbf{x}_j)\right)$$

where  $\oplus$  is a permutation invariant aggregation function

■ The most general version of GNNs are message passing networks, where \u03c6 is a neural network itself. The message received by node i is computed from both the feature vectors of node i and j [Gilmer et al., 2017]

# **DISCIMINATIVE POWER OF GNNS**

#### Graph isomorphism

Let G and H be two graphs with vertex sets V(G) and V(H). A graph isomorphism f between G and H is defined as a function  $f : V(G) \mapsto V(H)$  such that for all vertices u, v adjacent in G it follows that f(u) and f(v) are adjacent in H.

- Two graphs are called isomorphic if there exists a graph isomorphism
- Finding graph isomorphisms is difficult, i.e. for a graph with n nodes we have to test n! node permutations
- Weisfeiler-Lehman Isomorphism Test can be used as a computationally fast heuristic

#### Weisfeiler-Lehman Isomorphism Test (1-WL) [Weisfeiler and Leman, 1968]

For both graphs G and H, assign each node i an initial node color  $x_i = 1$ . Within each iteration, the node color is updated using a given hash function according to the update rule

$$x_i \leftarrow \operatorname{hash}\left(x_i, \left\{\left\{ \left. x_j \mid j \rightarrow i \right. \right\}\right\}\right) \,,$$

where  $\{\{\cdot\}\}\$  denotes a multiset. The hash function maps the current node color and the multiset of neighboring node colors to a new node color from a *discrete* set.

Nodes are partitioned according to their colors. The algorithm terminates if node partitions are stable. *G* and *H* pass the test if  $n_x(G) = n_x(H)$  for all *x*, where  $n_x(G) = \sum_{i \in G} \mathbb{1}_{x=x_i}$  is the number of occurrences of color *x* [Huang and Villar, 2021].

- Note that the feature vectors x<sub>i</sub> might never become stable, however, the node partitions will
- The Weisfeiler-Lehman Isomorphism Test has limited power
  - { Test fails }  $\rightarrow$  graphs are not isomorphic
  - Some graphs that pass the test are not isomorphic
- Example of non-isomorphic graphs that pass the test:



#### GRAPH ISOMORPHISM - k-WL TEST

- The k-WL test improves on this difficulty by coloring node sets of size k [Maron et al., 2019]
- The sub-graph structure of nodes in the k-tuples determine the initial k-tuple colors
- Colors are updated based on the colors of the neighborhood of k-tuples, which is all tuples where one node has been replaced by another node
- 1-WL and 2-WL test are equivalent in discriminative power
- Otherwise k + 1-WL is more powerful than k-WL

#### **EXPRESSIVE POWER OF GRAPH NETWORKS**

Recall the update rule of graph neural networks

$$\mathbf{x}'_i = \phi\left(\mathbf{x}_i, \bigoplus_{j \to i} \psi(\mathbf{x}_i, \mathbf{x}_j)\right)$$

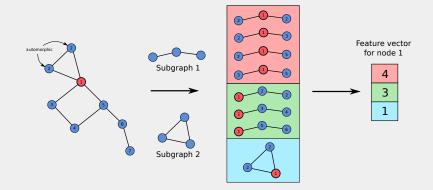
- The rule is identical to the hash function of the 1-WL test
- GNNs are therefore only as powerful as the 1-WL test in discriminating graphs [Xu et al., 2018]
- Although we seem to need permutation equivariance for graph neural networks, we then loose essential information on the graph structure and cannot distinguish between all graphs

#### **BEYOND 1-WL**

- There exist several strategies to increase the power of GNNs beyond 1-WL:
  - Design models equivalent to the k-WL test with k > 1 [Maron et al., 2018, Maron et al., 2019, Keriven and Peyré, 2019, Azizian and Lelarge, 2020]
  - Specific pre-coloring of nodes to encode positional information<sup>3</sup>
    - Pre-coloring based on graph substructures [Bouritsas et al., 2022]
    - Using simplicial- or cell-complexes
       [Bodnar et al., 2021b, Bodnar et al., 2021a]
    - Graph Laplacian eigenvectors [Dwivedi et al., 2020]
  - Work with sub-graphs and local equivariance, e.g. natural graph networks [de Haan et al., 2020]

<sup>3</sup>Remember that the WL test uses the same initial color for all nodes

#### SUBGRAPH ISOMORPHIC COUNTING



 Features encode local environment through subgraph counting [Bouritsas et al., 2022]

# NATURAL GRAPH NETWORKS (NGNS)

Recall the update function of CGNNs

$$\mathbf{X}_{i}' = \sigma \left( \sum_{j \to i} W \mathbf{X}_{j} \right)$$

NGNs [de Haan et al., 2020] generalize this update formula as follows

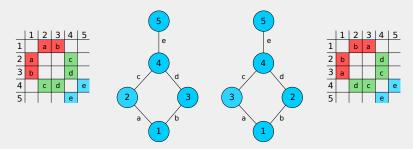
$$\mathbf{x}_{i}^{\prime} = \sigma \left( \sum_{j \to i} W_{ij}^{\mathsf{G}} \mathbf{x}_{j} \right)$$

i.e. the weight matrix depends on the graph G and the edge (i, j).

- Isomorphic graphs share the same weights
- Automorphic graphs constrain the weight matrices

## NATURAL GRAPH NETWORKS (NGNS)

- Automorphic graphs constrain weight matrices
- Given the following graph G and assume for simplicity that  $W_{ij}^G = W_{ji}^G$



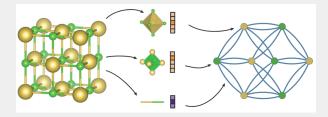
• Edges a, b and c, d must have the same weights, i.e.  $W_{12}^G = W_{13}^G$  and  $W_{24}^G = W_{34}^G$ 

## NATURAL GRAPH NETWORKS (NGNS)

- Natural graphs in this form are too general, i.e. each set of isomorphic graphs receives its own weights
- With this minimal weight sharing no learning across graphs is possible
- Local natural graphs (LNGs) solve this issue by looking at small sub-graphs

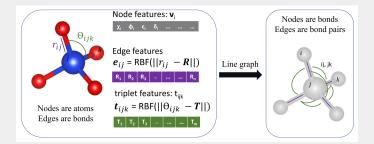
# **GNNS IN PRACTICE**

### CGCNN



- Crystal Graph Convolutional Neural Network (CGCNN) [Xie and Grossman, 2018], one of the first and simplest crystal graph networks
- Initial node features: Group number, periodic number, electronegativity, covalent radius, valence electrons, first ionization energy, electron affinity, block, atomic volume
- Initial edge features: Atom distance

### ALIGNN



#### [Choudhary and DeCost, 2021]

## ALIGNN

- ALIGNN [Choudhary and DeCost, 2021] performs edge-gated graph convolution simultaneously on both the atomistic bond graph and the line graph
- Atomistic bond graph: Atoms are nodes, bonds are edges
  - Initial node features: Electronegativity, group number, covalent radius, valence electrons, first ionization energy, electron affinity, block, and atomic volume
  - Initial edge features: RBF expanded interatomic bond distances
- Line graph: Bonds are nodes, bond pairs with one common atom (or atom triplets) are edges. Nodes correspond to bonds in the atomistic bond graph
  - Node features: Edge features of the bond graph
  - Initial edge features: RBF expanded bond angles

27

- Review of graph neural networks [Zhou et al., 2020]
- Geometric deep learning [Bronstein et al., 2021]

GNNs are implemented in PyTorch Geometric:

- Website: https://pyg.org/
- Documentation: https://pytorch-geometric.readthedocs.io

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